
GETTING STARTED WITH ARM SAM7S64

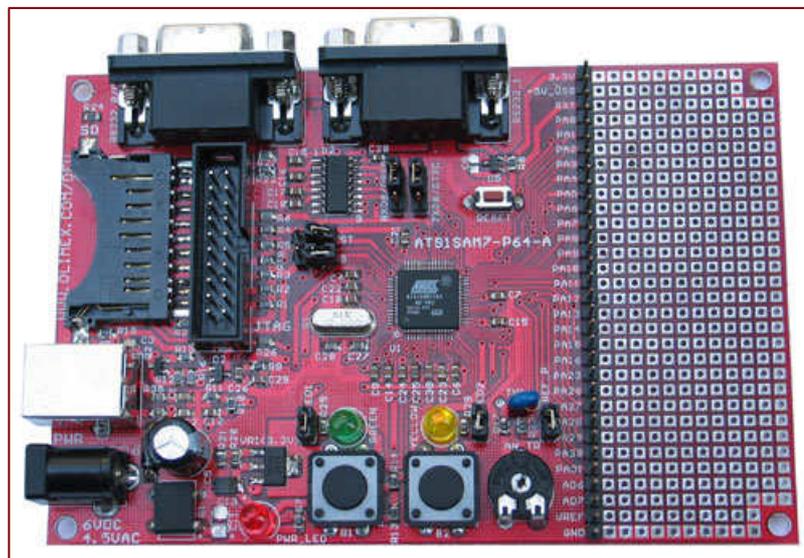
Part 1

Keywords: Get started, Microcontroller, ARM, SAM7S64, ARM-JTAG, IAR EWARM

1. Introduction

Olimex AT91SAM7-P64-A development board provides a low cost alternative to evaluation of the Atmel's AT91SAM7S low pin-count 32-bit ARM RISC processor. Features of the AT91SAM7-P64-A development board as below.

- MCU: AT91SAM7S64 16/32 bit ARM7TDMI™ with 64K Bytes Program Flash, 16K Bytes RAM, USB 2.0, RTT, 10 bit ADC, 2x UARTs, TWI (I²C), SPI, 3x 32bit TIMERS, 4x PWM, SSC (I²S), WDT, PDC (DMA) for all peripherals, up to 55MHz operation
- standard JTAG connector with ARM 2x10 pin layout for programming/debugging with ARM-JTAG
- USB connector
- Two channel RS232 interface and driver
- SD/MMC card connector
- two push-buttons
- trimpot connected to ADC
- thermistor connected to ADC
- two status LEDs
- single power supply: 6V – 9V DC/AC required
- 18.432 MHz crystal
- Full Schematics available



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2. Hardware Requirement

Besides the AT91SAM7-P64 board, we need few additional hardware to get started:

1. A PC running Windows XP
2. Olimex ARM JTAG debugger
3. USB Cable (Type A <-> Type B)
4. Straight parallel port extender cable (optional)
5. 6V – 9V DC transformer

3. Software Requirement

1. Free 32KB Kickstart edition of IAR Embedded Workbench Kickstart for ARM™ V4.30A (EWARM) downloaded from www.iar.se
2. H-JTAG Server downloaded from www.olimex.com or www.TechToys.com.hk under "*Tools and Software->ARM JTAG*" section. The latest version is v0.3.1.
3. An example program downloaded from www.TechToys.com.hk under "*ARM Boards->Atmel SAM7-P64->Documents->Getting Started with SAM7 (30 pages Guide) & source code*".
4. SAM Boot Assistant (SAM-BA) obtained from www.at91.com

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4. Prepare the IDE

4.1 Installation of EWARM

The first thing to do is to download a copy of the "IAR Embedded Workbench Kickstart for ARM" V4.30A (EWARM) from <http://supp.iar.com/Download/SW/?item=EWARM-KS32> and get it installed. After download, double click on the installation file (93MB). Complete the registration afterwards.



From Windows Start menu, there will be a program as IAR Embedded Workbench. My PC have IAR Embedded Workbench KickStart for MSP430 also, so there is another 'IAR Embedded...MSP430' above the ARM KickStart. This MSP430 workbench is not relevant to ARM development.



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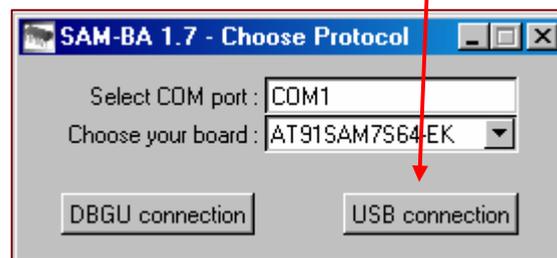
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4.2 Installation of SAM Boot Assistant (SAM-BA)

SAM-BA is a software provided by Atmel to in-circuit program AT91 devices via RS232 or USB. **NO PROGRAMMER IS REQUIRED!** From www.at91.com, download SAM-BA and get it installed. There is not much difficulty with it. Restart the PC after installation.



When SAM-BA starts, there is a dialog box asking for connection protocol as below. Our board is AT91SAM7S64-EK compatible. Select AT91SAM7S64-EK. We may use either serial connection or USB connection. Let's use USB connection because the board will be powered by the USB, no need to use external power for the SAM board in this case. Click on **USB connection** button.



I did that, and I have got an error message as below!



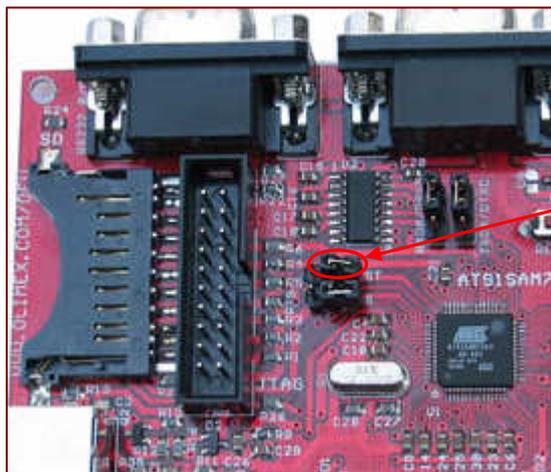
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The reason is that we need to perform SYSTEM RECOVERY PROCEDURE:

1. Shutdown the board (unplug USB cable in our case),
2. Before power up the board, the TST (pin 40), PA0/PGMEN0 (pin 48), PA1/PGMEN1 (pin 47), and PA2/PGMEN2 (pin 44) signals must be set (high). On Olimex AT91SAM7-P64-A evaluation board, short only the TEST jumper to set the TST signal (PA0, PA1, PA2 are all set by default via internal pull-up resistors),



TEST JUMPER: TST (pin 40)

3. Power up the board (re-connect the USB cable) and wait 10 sec,
4. Shut down the board (remove USB cable) and remove the TEST jumper,
5. Power up the board (re-connect USB cable): The board is now working with the *SAM-BA Boot* application from flash and waiting for connection through USB or DBGU port. Click on USB connection. The atm6124USB driver used by SAM-BA will be automatically installed.



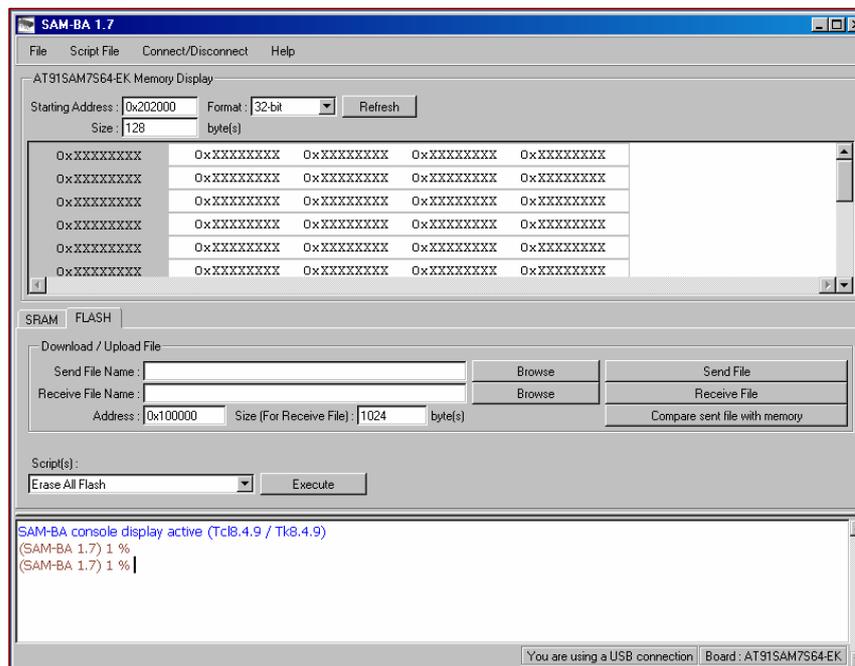
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SAM-BA will start. From here, we may download any executable file to our SAM7 ARM mcu (browse to *.bin file -> Send file -> press RESET button onboard). Visit our web page to find a simple LED blink binary file in *.bin format to simply blink the GREEN and YELLOW LEDs. Else, you may also visit www.at91.com for an executable version of Mass Storage application for SAM7S64.

Indeed, I was able to turn my SAM board to a USB thumb drive, though it was only a miserable 39KB FAT-format drive because it used the internal flash of the SAM7S64 for storage. Nevertheless, we may request the full source code from Atmel to learn implementation of a FAT file system in SAM. Because there is a mmc socket onboard exclusive with our SAM board, it will be possible for us to extend the file system to mmc cards and use the SAM board for any data logging project.



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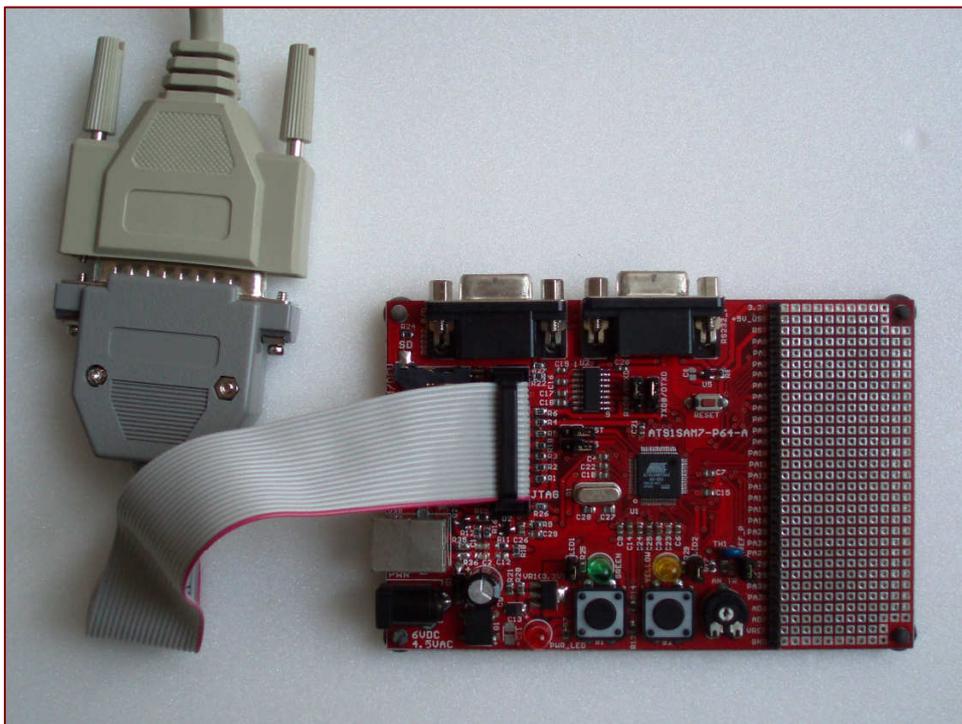
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4.3 Installation of ARM-Jtag and H-JTAG driver

Download H-JTAG V0.3.1 driver (under Tools & software-> ARM JTAG section) from our web site, unzip and install. After installation, there will be a short-cut on desktop and a non-plug&play device driver installed in the PC system's device manager.



Connect the ARM-JTAG via 20-pin IDC cable to the JTAG interface on SAM7 board as below. Connect ARM-JTAG to parallel port of your PC, use a 25-pin straight parallel port extension cable if necessary. Power-up the development board by connection of a 6V-9V DC transformer to PWR socket (or just leave the USB cable for power).

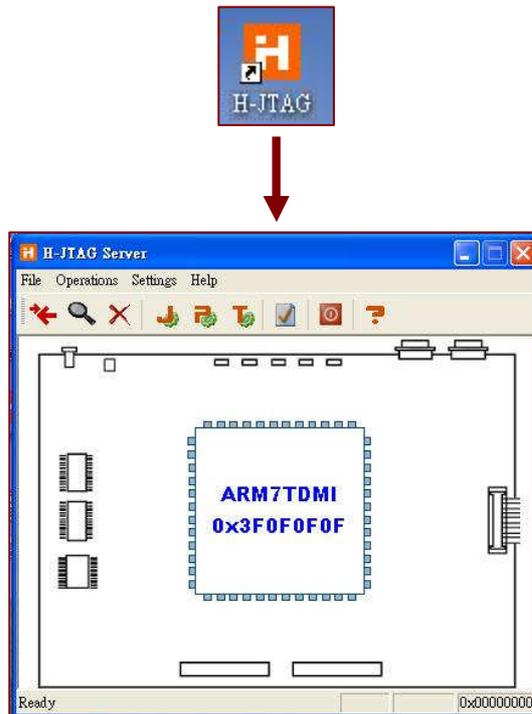


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Double click H-JTAG short-cut to start the driver. The following screen program can be seen. This screen represents a successful connection between the PC and the SAM7S64 mcu via JTAG interface. From now on, we can minimize the H-JTAG Server and let it run in background.



If you don't see successful connection above, select **Settings** to customize the pin assignment as follows:

Wiggler (Predefined), that means we are using a wiggler clone.

TMS <-> Pin3 of parallel port (default)

TCK <-> Pin4 (default)

TDI <-> Pin5 (default)

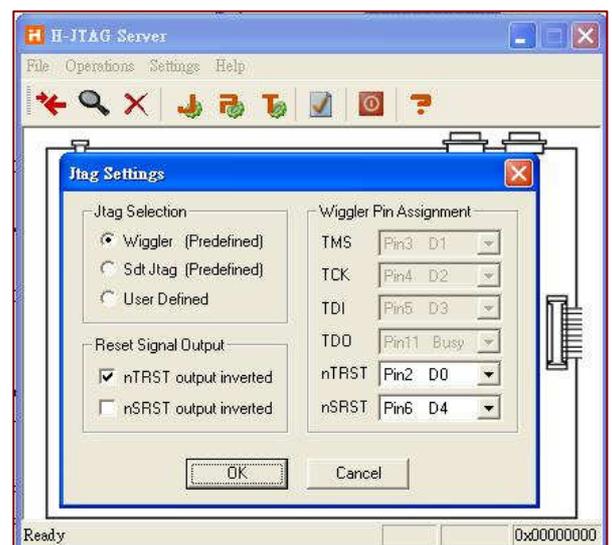
TDO <-> Pin11(default)

nTRST <-> Pin2

nSRST <-> Pin6

Check nTRST output inverted

Make sure the parallel port setting of your PC matches 0x378 LPT1.



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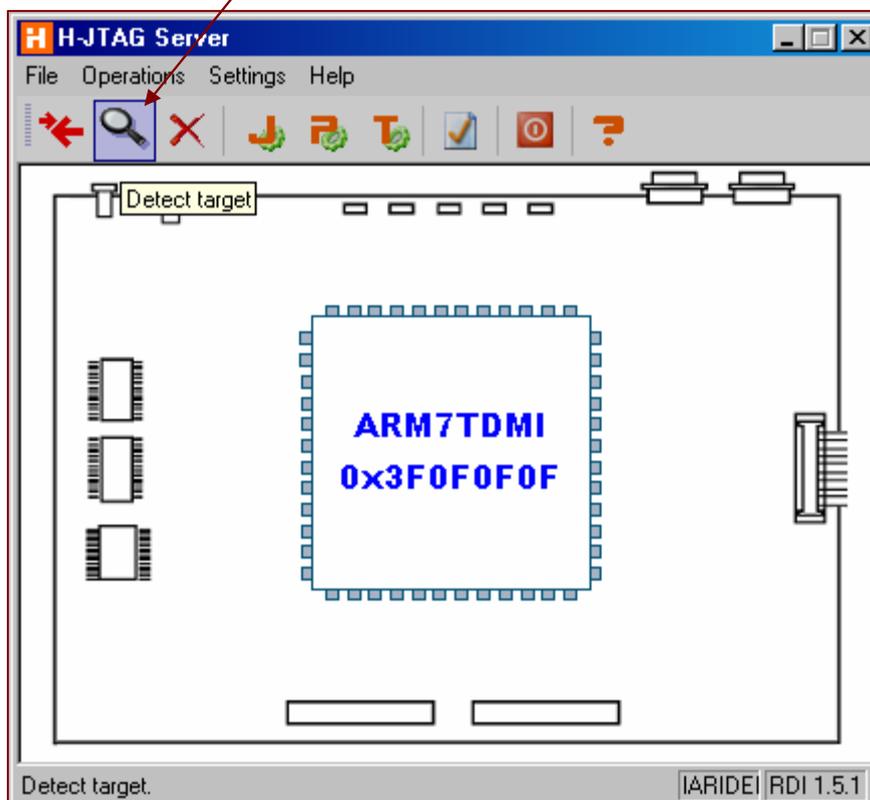
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Click on the magnifying glass icon to reconnect to target (SAM7S64 mcu). If you still cannot succeed in connection, please refer to Appendix A for remarks.

After the H-JTAG Server has made a successful connection with the target board, there will be an H-SERVER icon at the lower left corner of the desktop. This icon will change to a "PLAY" icon during debug.



Magnifying glass to reconnect



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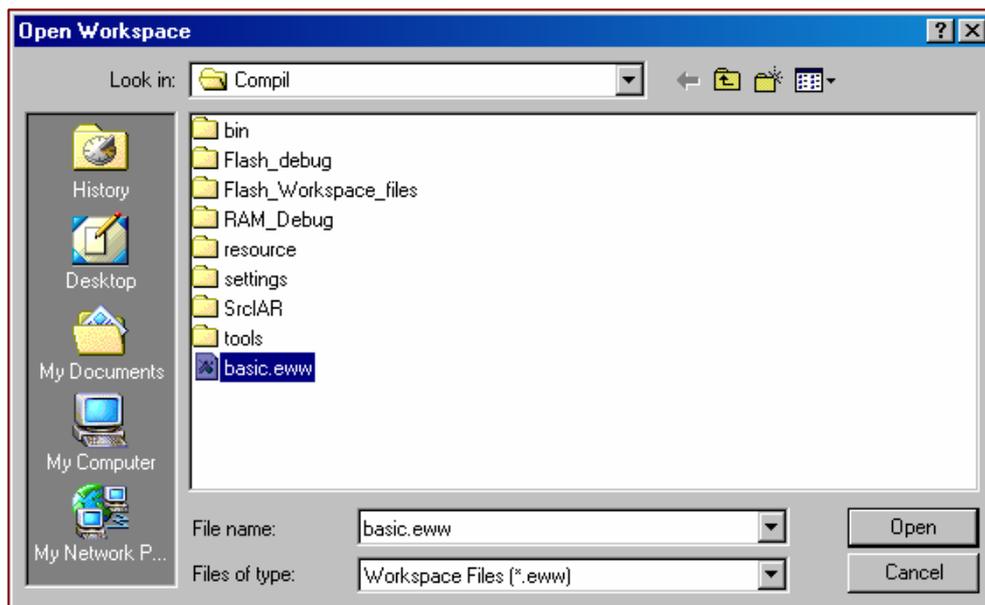
5. The first project (Let's blink the LEDs!)

Download an application from us at www.TechToys.com.hk and unzip the program to a convenient place. It is under ARM Boards -> Atmel SAM7-P64 -> Documents -> [Getting Started with SAM7](#) (30 pages Guide) & [source code](#). Place the project folder anywhere you like. In my case, I have placed it under D:\SAM7S64.

Launch EWARM from Windows Start Menu, browse to D:\SAM7S64\AT91SAM7S-BasicTools\Compil\basic.eww



Click Open.

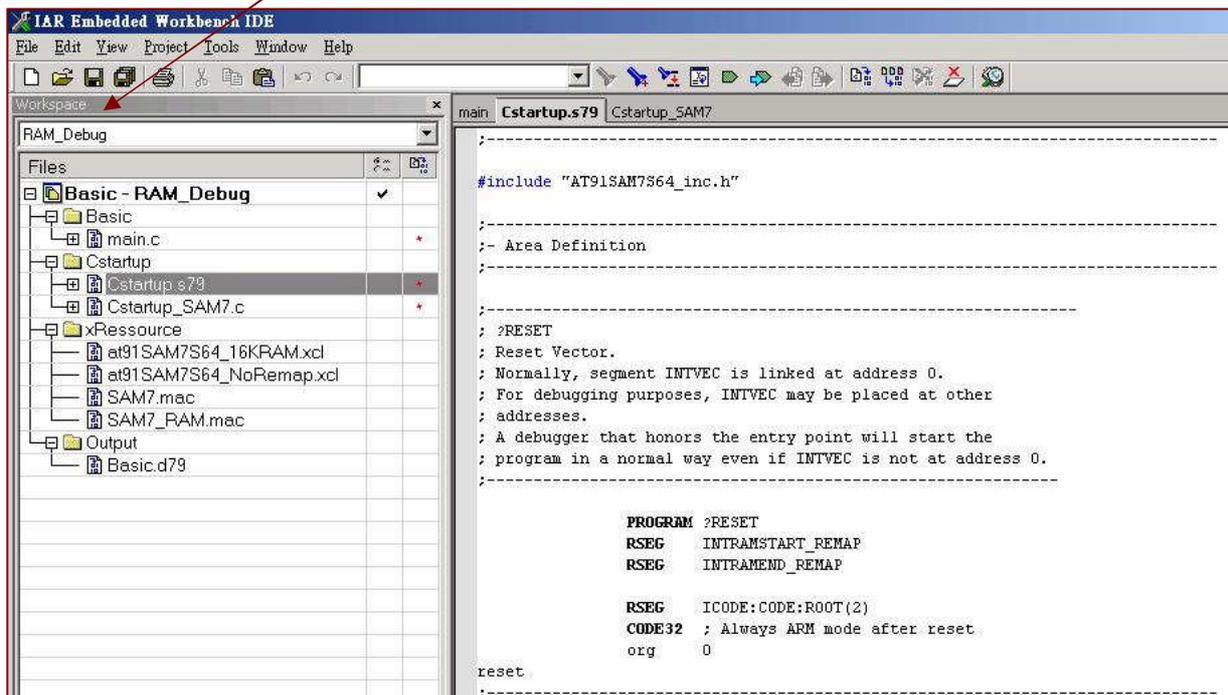


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You will see the workspace opened. The left panel is the workspace panel. Make sure the drop-down menu have RAM_Debug selected.



This project is not much different from an example available under the installation directory of EWARM. I just modified the board.h file to suit our SAM board. Besides, I have also modified some of the functions provided by the standard library to see how the program run. Example is :

```
// AT91F_PMC_EnablePeriphClock ( AT91C_BASE_PMC, 1 << AT91C_ID_PIOA ) ;  
*AT91C_PMC_SCER = AT91C_CKGR_MOSCEN; // main oscillator enable  
*AT91C_PMC_PCER = 1<<AT91C_ID_PIOA; // peripheral clock enable
```

Please see comment in main.c and board.h for modifications made.

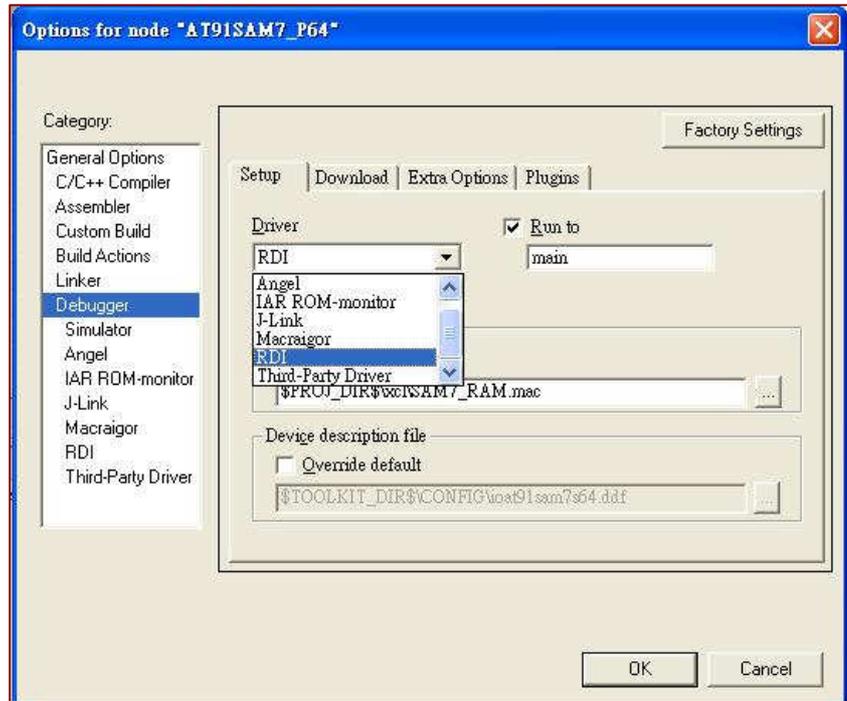
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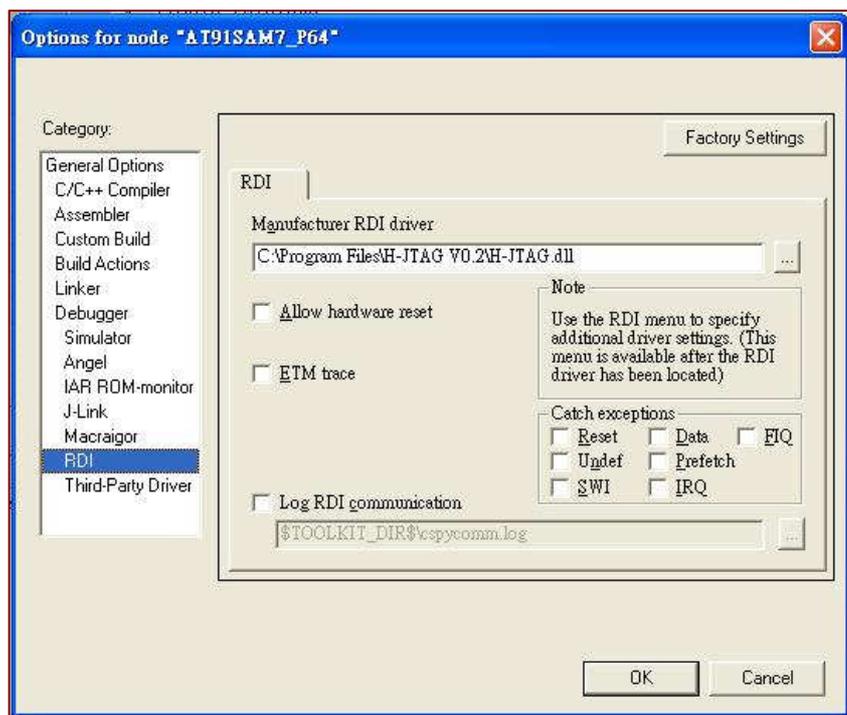
Keywords: Get started, Microcontroller, ARM, SAM7S64, ARM-JTAG, IAR EWARM

Let's debug our application as follows:

Under **Project->Options**, select category **Debugger**. There are several options built-in the EWARM. H-JTAG Server is RDI compatible, so we select RDI as the C-SPY Driver. Check **Run to** check-box, and put in **main** in the text box. This means we jump to the c-function main () in main.c when debug. If this option is not checked, we will jump to the first line of code of Cstartup.s79 when debug.



Click on another instance of **RDI** underneath **Debugger**. Browse to the H-JTAG RDI driver (H-JTAG.dll) from the H-JTAG installation directory. Normally, it would be under C:\Program Files\H-JTAG V0.2\H-JTAG.dll. Finally press **OK** to save all settings.

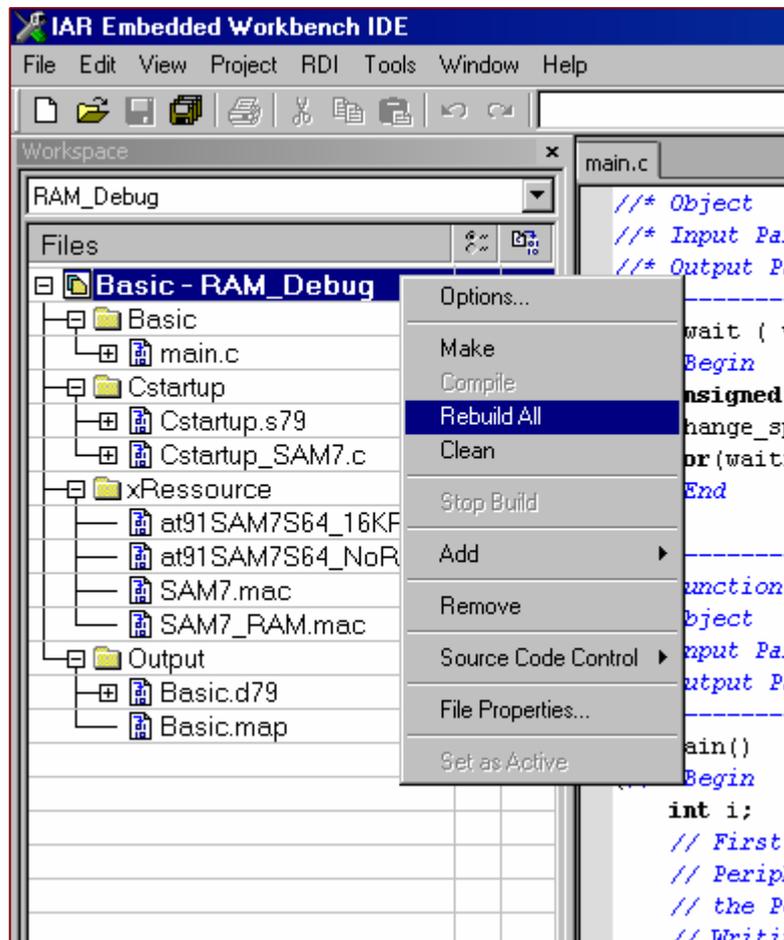


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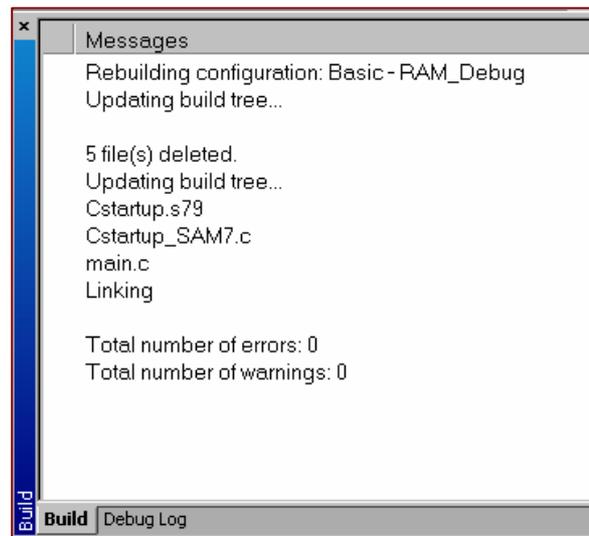
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Just to make sure we have all code compiled and linked, we may right click on the Basic - RAM_Debug workspace and select Rebuild All.



Build results show no error and warning.



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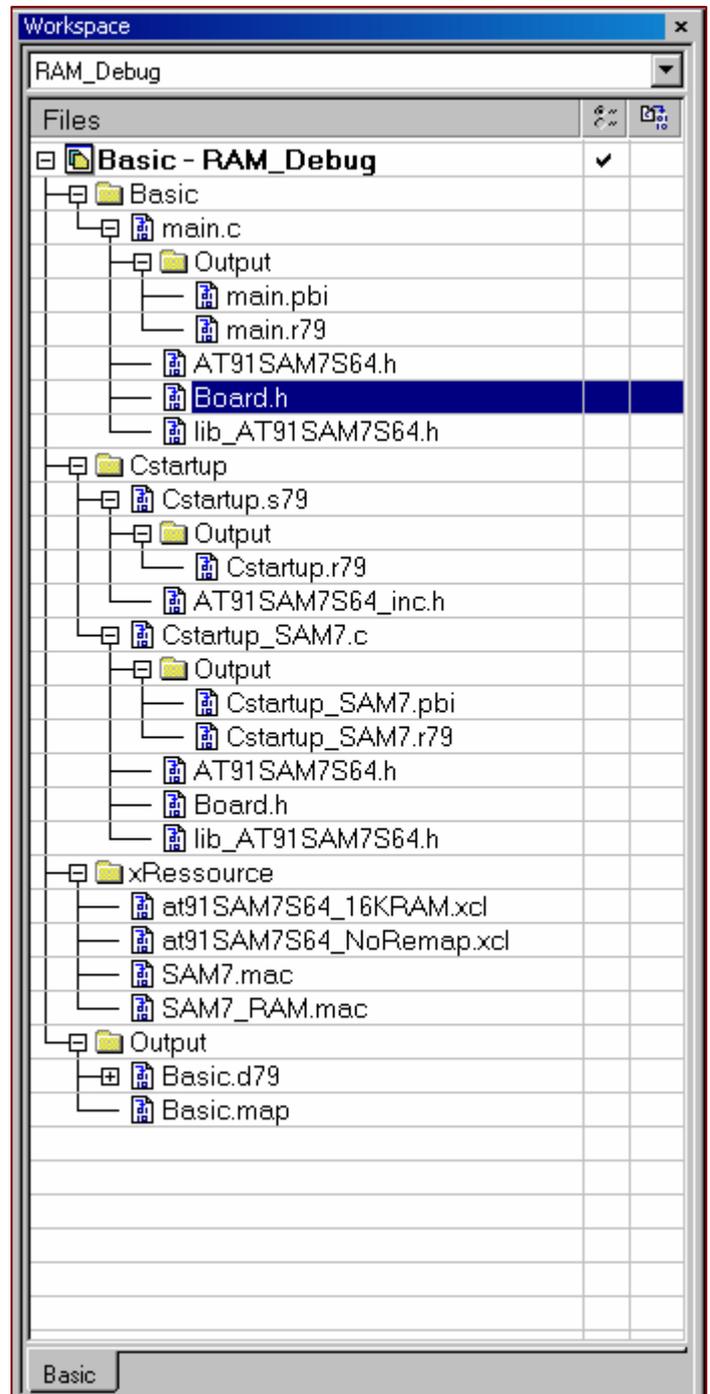
Expand each of the categories under the workspace. We can see all output files and their dependency.

Object files = *.r79

Linker command files = *.xcl

Macro files for debugger = *.mac

Output file for RAM-Debug = *.d79

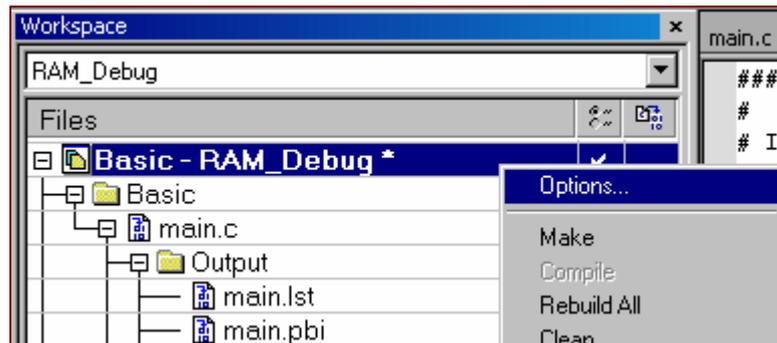


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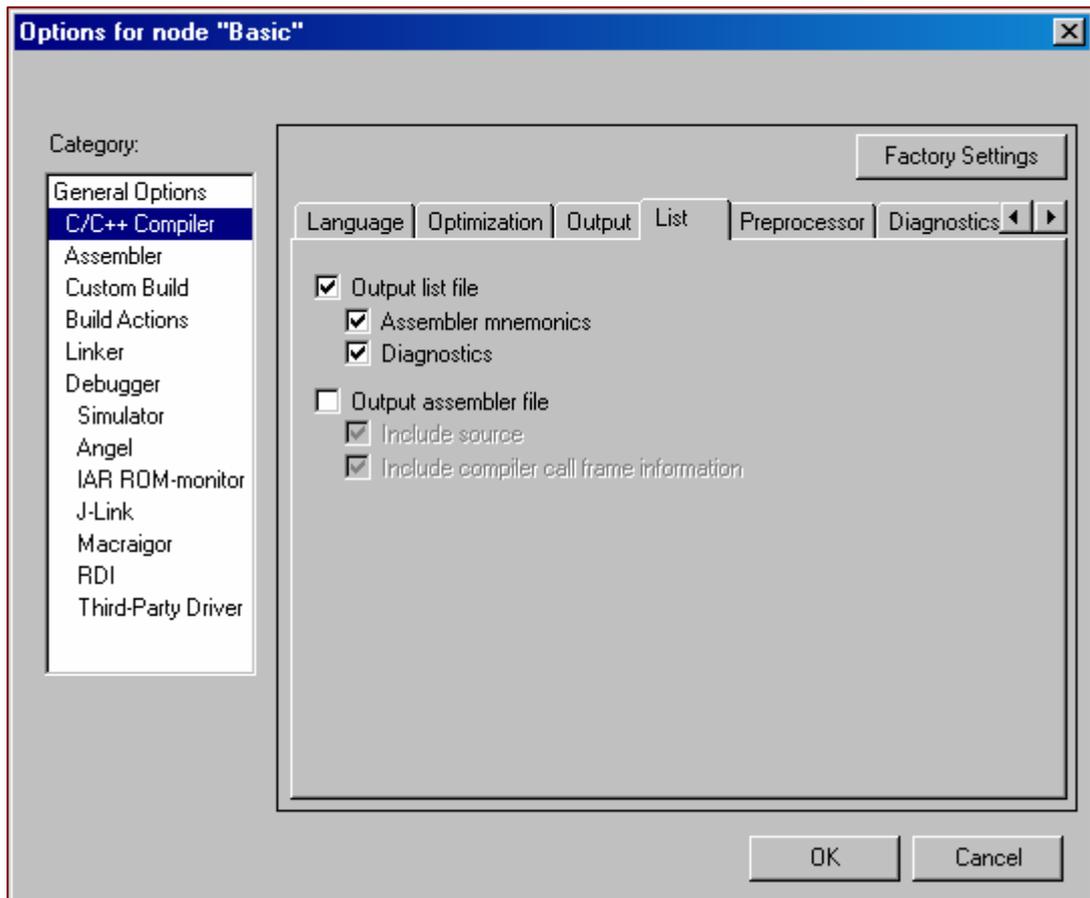
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It is possible for us to customize what file to output under the C compiler option. Right click on the project workspace, **Basic-RAM_Debug** -> **Options**



Select **C/C++ Compiler** under Category, select **List** tab. Check Output list file option. Rebuild All.

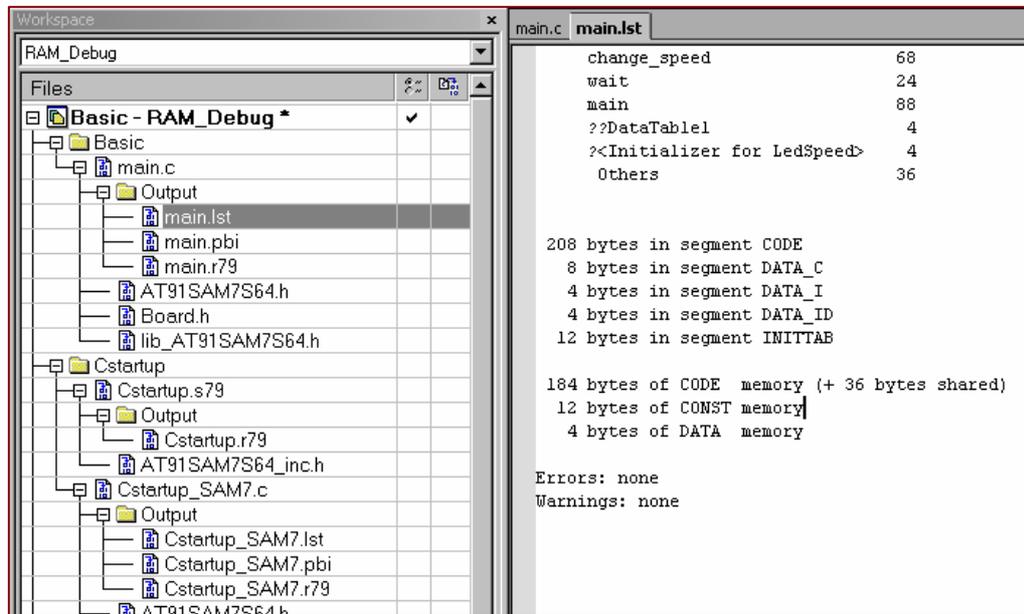


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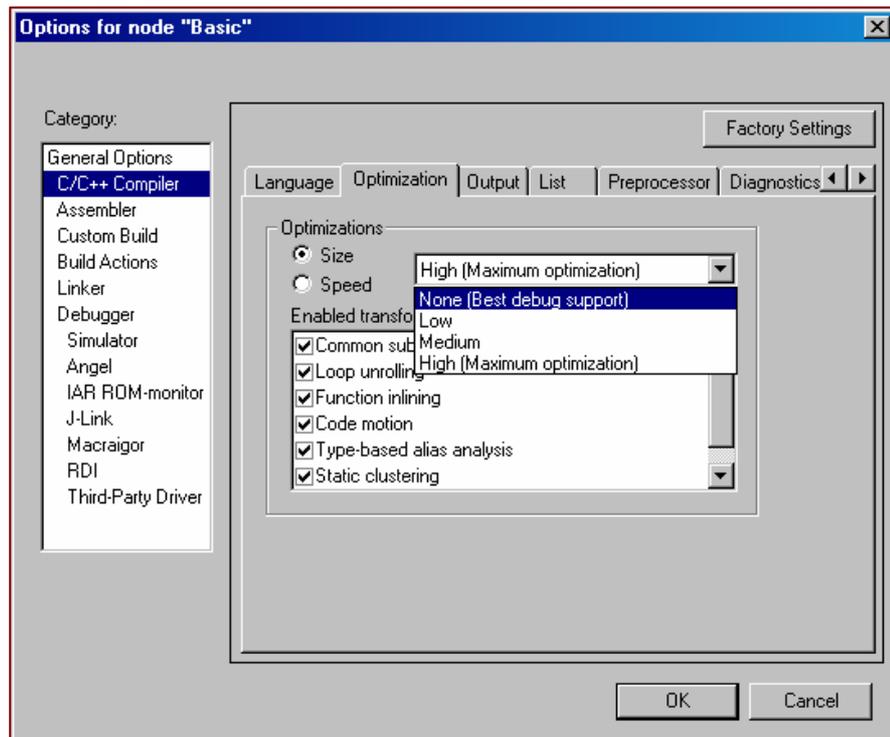
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Now we see a list file with an extension *.lst. Open main.lst and browse to the bottom, we can see the CODE segment data bytes and CODE memory usage.



Go to workspace Options again. Under **C\C++ compiler -> Optimization -> select None(Best debug support)**.

Rebuild All.

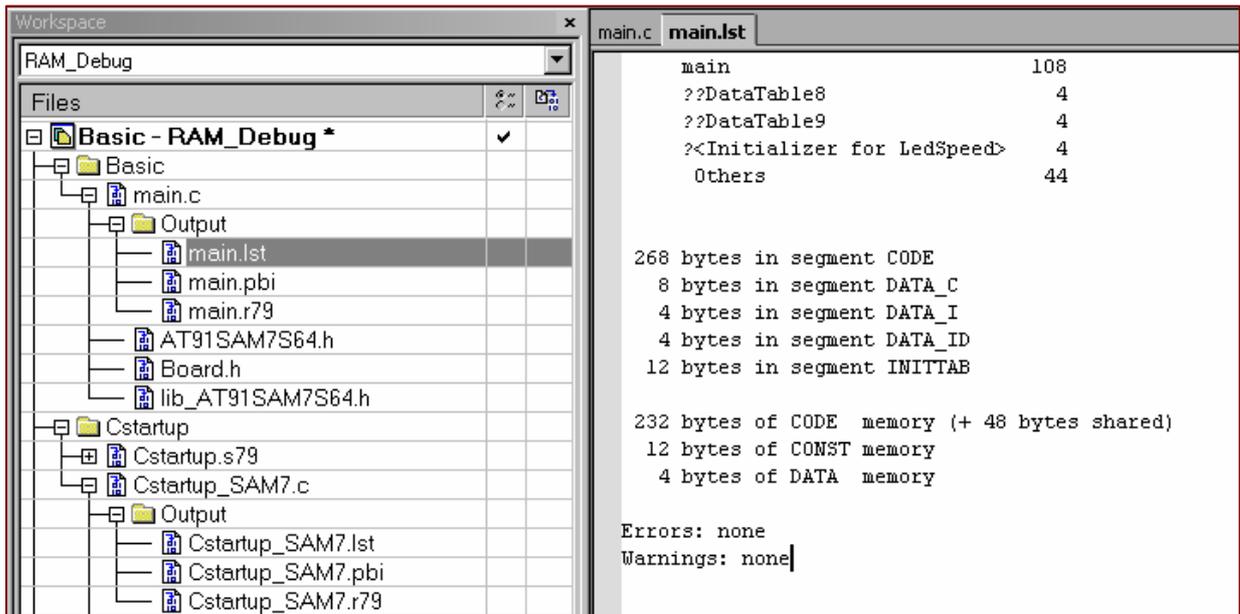


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Compare the build results with maximum optimization & No optimization, we can see the difference in both CODE and memory usage!



The screenshot shows the IAR EWARM workspace. On the left, the 'Files' pane displays a project tree for 'Basic - RAM_Debug'. The tree includes folders for 'Basic' and 'Cstartup', with sub-folders for 'Output'. Files listed include 'main.c', 'main.lst', 'main.pbi', 'main.r79', 'AT91SAM7S64.h', 'Board.h', 'lib_AT91SAM7S64.h', 'Cstartup.s79', 'Cstartup_SAM7.c', 'Cstartup_SAM7.lst', 'Cstartup_SAM7.pbi', and 'Cstartup_SAM7.r79'. The 'main.lst' file is selected. On the right, the linker output window shows the following data:

Symbol	Size
main	108
??DataTable8	4
??DataTable9	4
?<Initializer for LedSpeed>	4
Others	44

268 bytes in segment CODE
8 bytes in segment DATA_C
4 bytes in segment DATA_I
4 bytes in segment DATA_ID
12 bytes in segment INITTAB

232 bytes of CODE memory (+ 48 bytes shared)
12 bytes of CONST memory
4 bytes of DATA memory

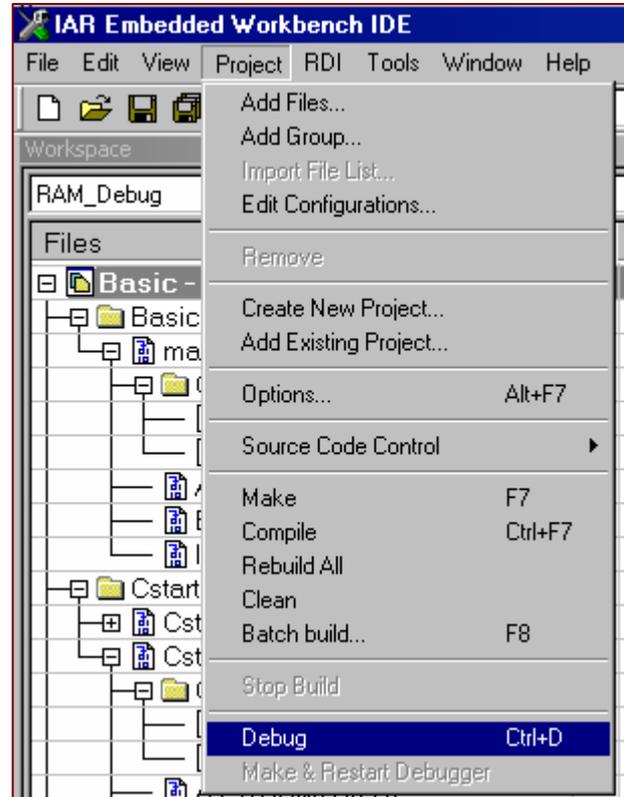
Errors: none
Warnings: none

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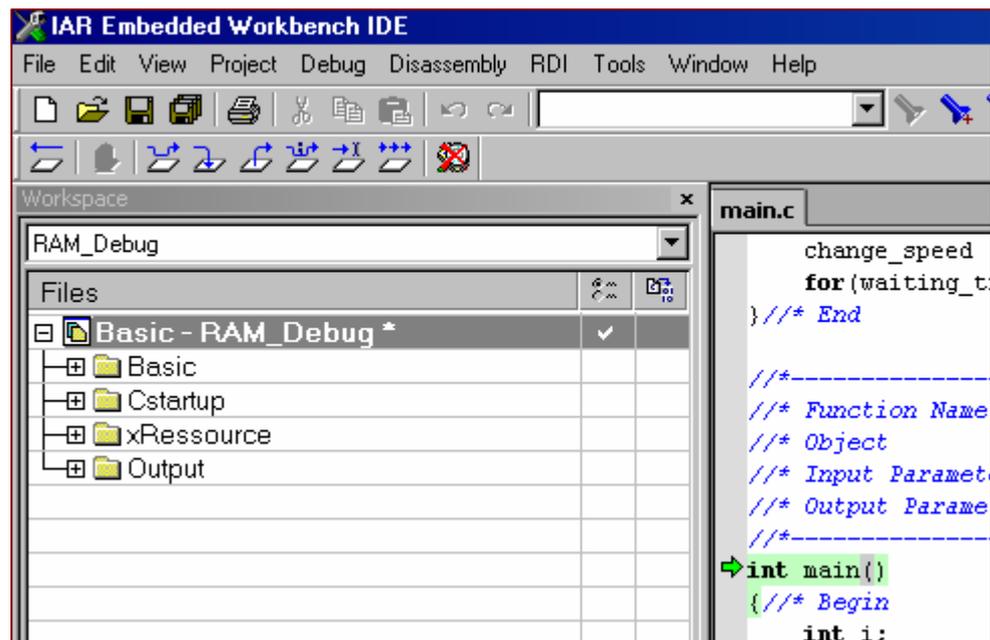
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Under **Project** -> **Debug**, select **Debug**. Before that, make sure the H-JTAG server has started and successfully connected to the board as described in previous section.



If everything goes smooth, we would be able to debug our first application under the debug window. The green pointer stops at main().



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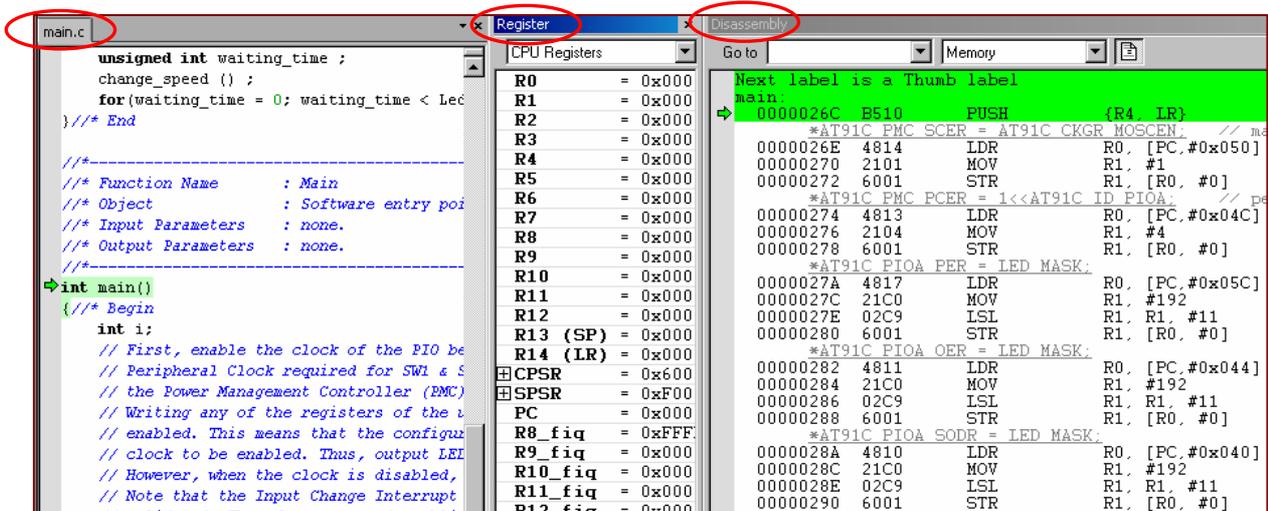
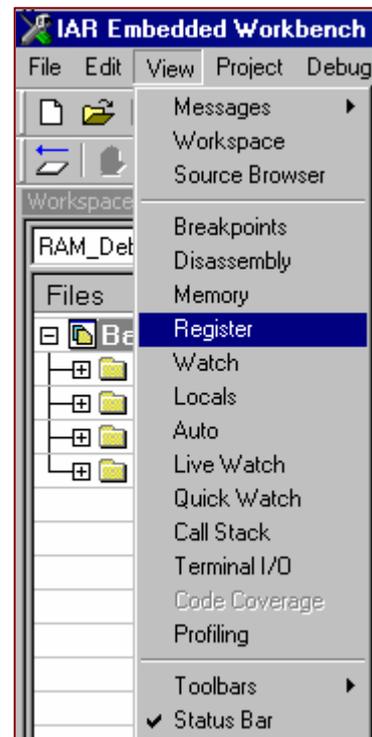
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The following short-keys allow us to perform stepping.

Go	F5
Step Over	F10
Step Into	F11
Step Out	Shift+F11

Click on **View** menu->**Register**.
One more time, click on **View** menu->**Disassembly**.

Now we see the source file main.c, Register map, and the Disassembly listing on the same Window.



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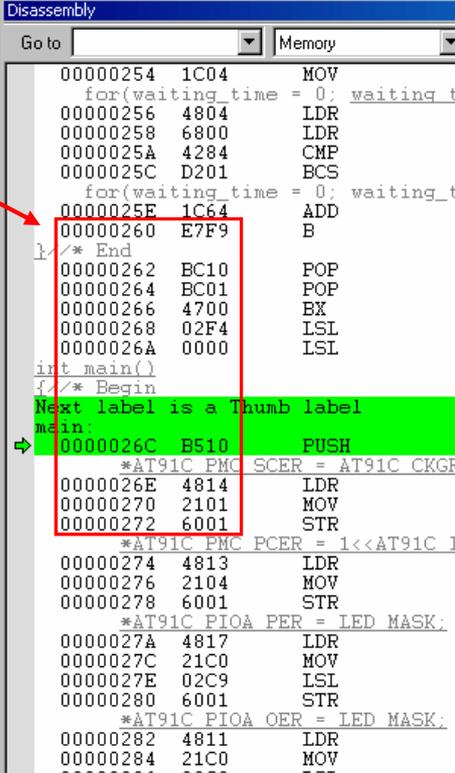
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Click on **View** menu->**Memory**.

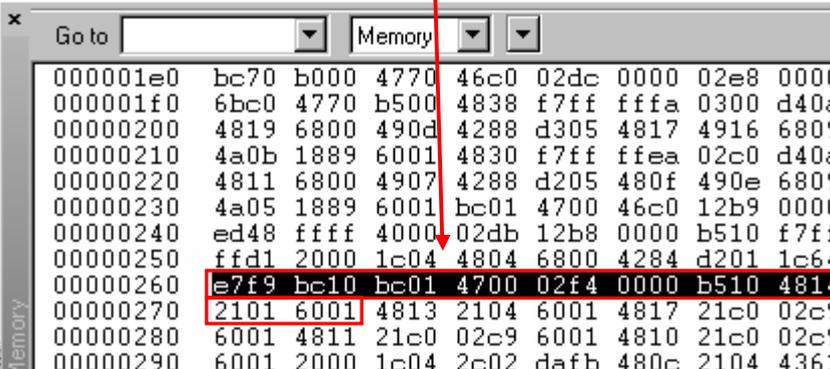
Comparing the memory contents between the Memory map and Disassembly listing, I have got much insight of what the program was all about. Each instruction after compilation has been assigned to an address in the memory space. For example, our first c syntax

```
*AT91C_PMC_SCER = AT91C_CKGR_MOSCCEN;  
has been compiled to three assembly syntax  
0x0000026E 4814 LDR R0,[PC,#0x050]  
0x00000270 2101 MOV R1,#1  
0x00000272 6001 STR R1,[R0,#0]
```

From the memory map, we see the machine code 4814, 2101, 6001 at the addresses 0x026E, 0x0270, and 0x0272 respectively.



```
Disassembly  
Go to [ ] Memory [ ]  
00000254 1C04 MOV  
for(waiting_time = 0; waiting_t  
00000256 4804 LDR  
00000258 6800 LDR  
0000025A 4284 CMP  
0000025C D201 BCS  
for(waiting_time = 0; waiting_t  
0000025E 1C64  
00000260 E7F9 B  
/* End  
00000262 BC10 POP  
00000264 BC01 POP  
00000266 4700 BX  
00000268 02F4 LSL  
0000026A 0000 LSL  
int main()  
/* Begin  
Next label is a Thumb label  
main:  
→ 0000026C B510 PUSH  
*AT91C_PMC_SCER = AT91C_CKGR  
0000026E 4814 LDR  
00000270 2101 MOV  
00000272 6001 STR  
*AT91C_PMC_PCER = 1<<AT91C_I  
00000274 4813 LDR  
00000276 2104 MOV  
00000278 6001 STR  
*AT91C_PIOA_PER = LED_MASK;  
0000027A 4817 LDR  
0000027C 21C0 MOV  
0000027E 02C9 LSL  
00000280 6001 STR  
*AT91C_PIOA_OER = LED_MASK;  
00000282 4811 LDR  
00000284 21C0 MOV  
00000286 02C9 LSL
```



Address	Hex							
000001e0	bc70	b000	4770	46c0	02dc	0000	02e8	0000
000001f0	6bc0	4770	b500	4838	f7ff	fffa	0300	d40a
00000200	4819	6800	490d	4288	d305	4817	4916	6809
00000210	4a0b	1889	6001	4830	f7ff	ffea	02c0	d40a
00000220	4811	6800	4907	4288	d205	480f	490e	6809
00000230	4a05	1889	6001	bc01	4700	46c0	12b9	0000
00000240	ed48	ffff	4000	02db	12b8	0000	b510	f7ff
00000250	ffd1	2000	1c04	4804	6800	4284	d201	1c64
00000260	e7f9	bc10	bc01	4700	02f4	0000	b510	4814
00000270	2101	6001	4813	2104	6001	4817	21c0	02c9
00000280	6001	4811	21c0	02c9	6001	4810	21c0	02c9
00000290	6001	2000	1c04	2c02	dafb	480c	2104	4361

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Use F11 to step into each line of codes to see what happen.

Main.c	Register View	Disassembly Listing
*AT91C_PMC_SCER = AT91C_CKGR_MOSCEN;	PC = 0x000026E	⇒ 0000026E 4814 LDR R0, [PC, #0x050] ;[0x2C0]=PMC_SCER (0xFFFF FC00)

PC = Program Counter @ the address 0x0000 026E

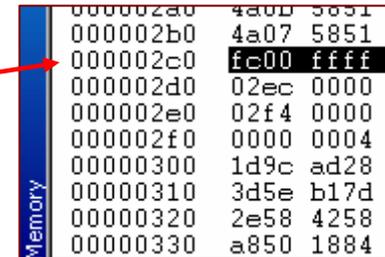
LDR R0,[PC,#0x050] ;assembler instruction for moving the value at the address [PC+0x050] to register R0

A comment generated from the assembly listing states that [0x2C0]=PMC_SCER (0xFFFF FC00).

0x2C0 = 0x270 + #0x050.

0x270 is the PC for the next line of code

Browse a little bit downwards on the Memory map, we have a value of 0xFFFF FC00, which is the address of the register PMC_SCER defined under AT91SAM7S64.h. It is now located at the program address of 0x2C0 after linking the program.



Memory	Value
000002a0	4a07 5851
000002b0	4a07 5851
000002c0	fc00 ffff
000002d0	02ec 0000
000002e0	02f4 0000
000002f0	0000 0004
00000300	1d9c ad28
00000310	3d5e b17d
00000320	2e58 4258
00000330	a850 1884

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Press F11 to single step. R0 and R1 registers assigned the value of 0xFFFF FC00 and 0x0000 0001, respectively.

Main.c	Register View	Disassembly Listing
*AT91C_PMC_SCER = AT91C_CKGR_MOSCCEN;	R0 = 0xFFFFFC00 R1 = 0x000002E8	0000026E 4814 LDR R0, [P → 00000270 2101 MOV R1, #1
*AT91C_PMC_SCER = AT91C_CKGR_MOSCCEN;	R0 = 0xFFFFFC00 R1 = 0x00000001	00000270 2101 MOV R1, #1 → 00000272 6001 STR R1, [R0

By single stepping 3 times, we ran the following code:

```

*AT91C_PMC_SCER = AT91C_CKGR_MOSCCEN; // map
0000026E 4814 LDR R0, [PC, #0x050]
00000270 2101 MOV R1, #1
00000272 6001 STR R1, [R0, #0]
    
```

Load the value 0xFFFF FC00, which is the address of the PMC register PMC_SCER (system clock enable register) located at the program address 0x2C0, to the working register R0 of the CPU.

Load the value 0x0000 0001 (AT91C_CKGR_MOSCCEN) to R1

Load the value held in R1 to the address held at [R0+0], that is 0xFFFF FC00 in this case. The result is writing a value of 0x0000 0001 to the address 0xFFFF FC00 (PMC_SCER).

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In conclusion, the result of the first c-code

***AT91C_PMC_SCER = AT91C_CKGR_MOSCN;**

is to write 0x0000 0001 to the PMC_SCER register, thus enabling the Processor clock by setting PCK=1.

Reading the manual of SAM7S64, I have learned more about PMC_SCER. A screen shot of page 189 as shown on right.

Continue stepping the codes until

***AT91C_PMC_PCER = 1<<AT91C_ID_PIOA;** finished.

Take a look at the Memory map down to the address 0xFFFF FFC0, we see the value of 0xFFFF FC08 (System Clock Status Register, PMC_SCSR) hold a value of 0x0000 0001, and 0xFFFF FC18 (Peripheral Clock Status Register, PMC_PCSR) hold a value of 0x0000 0004. It seems that because PMC_SCER and PMC_PCER are write-only registers, we cannot get viewed of the value directly from the Memory map. Instead, we need to rely on the PMC_SCSR and PMC_PCSR registers. Please correct me if I am wrong.

26.9.1 PMC System Clock Enable Register

Register Name: PMC_SCER

Access Type: Write-only

31	30	29	28	27	26	25	24
–	–	–	–	–	–	–	–
23	22	21	20	19	18	17	16
–	–	–	–	–	–	–	–
15	14	13	12	11	10	9	8
–	–	–	–	–	PCK2	PCK1	PCK0
7	6	5	4	3	2	1	0
9	–	–	–	–	–	–	PCK

- PCK: Processor Clock Enable
0 = No effect.
1 = Enables the Processor clock.
- UDP: USB Device Port Clock Enable
0 = No effect.
1 = Enables the 48 MHz clock of the USB Device Port.
(Does not pertain to AT91SAM7S32.)
- PCKx: Programmable Clock x Output Enable
0 = No effect.
1 = Enables the corresponding Programmable Clock output.

fffffc00	0000	0000	0000	0000	0001
fffffc10	0000	0000	0000	0000	0004
fffffc20	0601	0000	257c	0001	3f00
fffffc30	0007	0000	0000	0000	0000
fffffc40	0000	0000	0000	0000	0000
fffffc50	0000	0000	0000	0000	0000
fffffc60	0000	0000	0000	0000	000d
fffffc70	0000	0000	0000	0000	0000
fffffc80	0000	0000	0000	0000	0000
fffffc90	0000	0000	0000	0000	0000
fffffca0	0000	0000	0000	0000	0000
fffffcb0	0000	0000	0000	0000	0000
fffffcc0	0000	0000	0000	0000	0000
fffffd00	0000	0000	0000	0000	0000

GETTING STARTED WITH ARM SAM7S64

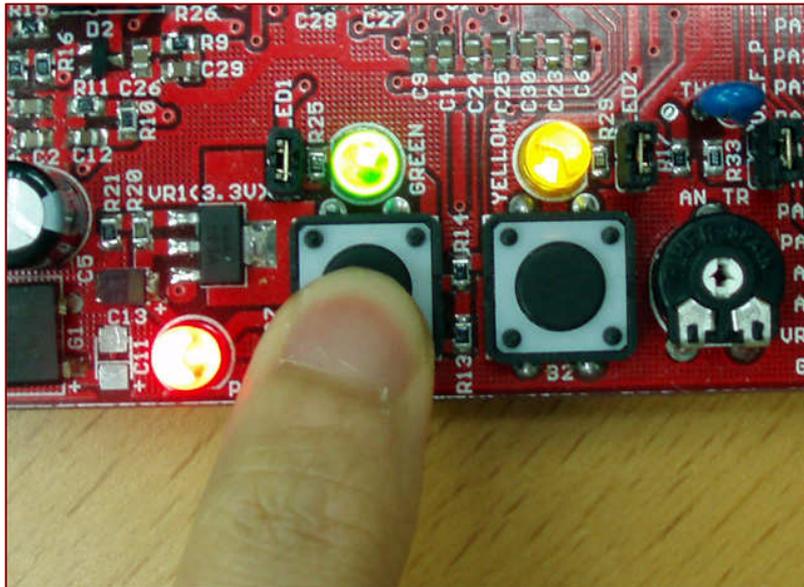
Part 1

Keywords: Get started, Microcontroller, ARM, SAM7S64, ARM-JTAG, IAR EWARM

Finally, press **(Go)**  to run the program.

Green and yellow LEDs blink.

Press B1 to increase the rate, B2 to decrease rate.



Press **(Break)**  to stop running, and step over the main loop by repeating F10 to watch LED blink.

```
for (;;)
{
    // Once a Shot on each led
    for ( i=0 ; i < NB_LEB ; i++ )
    {
        *AT91C_PIOA_CODR = led_mask[i]; //clear output data register, turn ON LED
        wait();
        *AT91C_PIOA_SODR = led_mask[i]; //set output data register, turn OFF LED
        wait();
    } // End for
} // End for
```

GETTING STARTED WITH ARM SAM7S64

Part 1

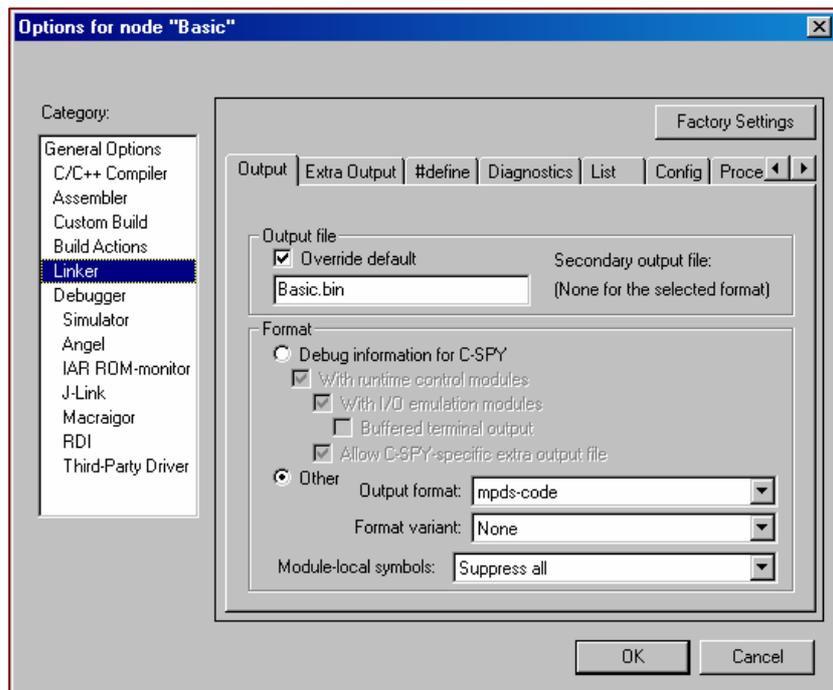
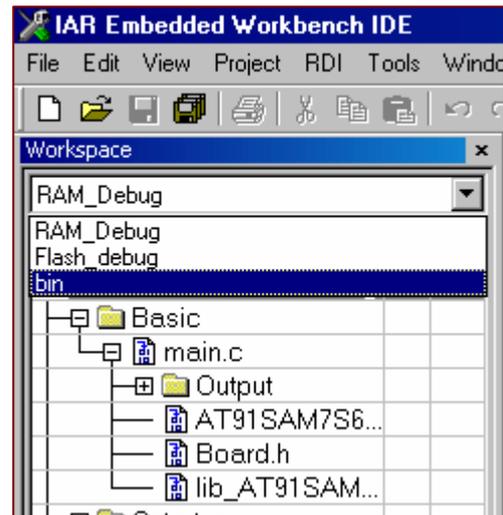
Keywords: Get started, Microcontroller, ARM, SAM7S64, ARM-JTAG, IAR EWARM

After debugging, it is time to produce an executable file for flash download.

Click on **Stop Debugging** icon to quit. 

Go back to workspace and select **bin** category under the drop-down menu.

There is a little bit different with the output option for *.bin output. Under Linker category, Output becomes Basic.bin, instead of Basic.d79 for RAM_Debug.

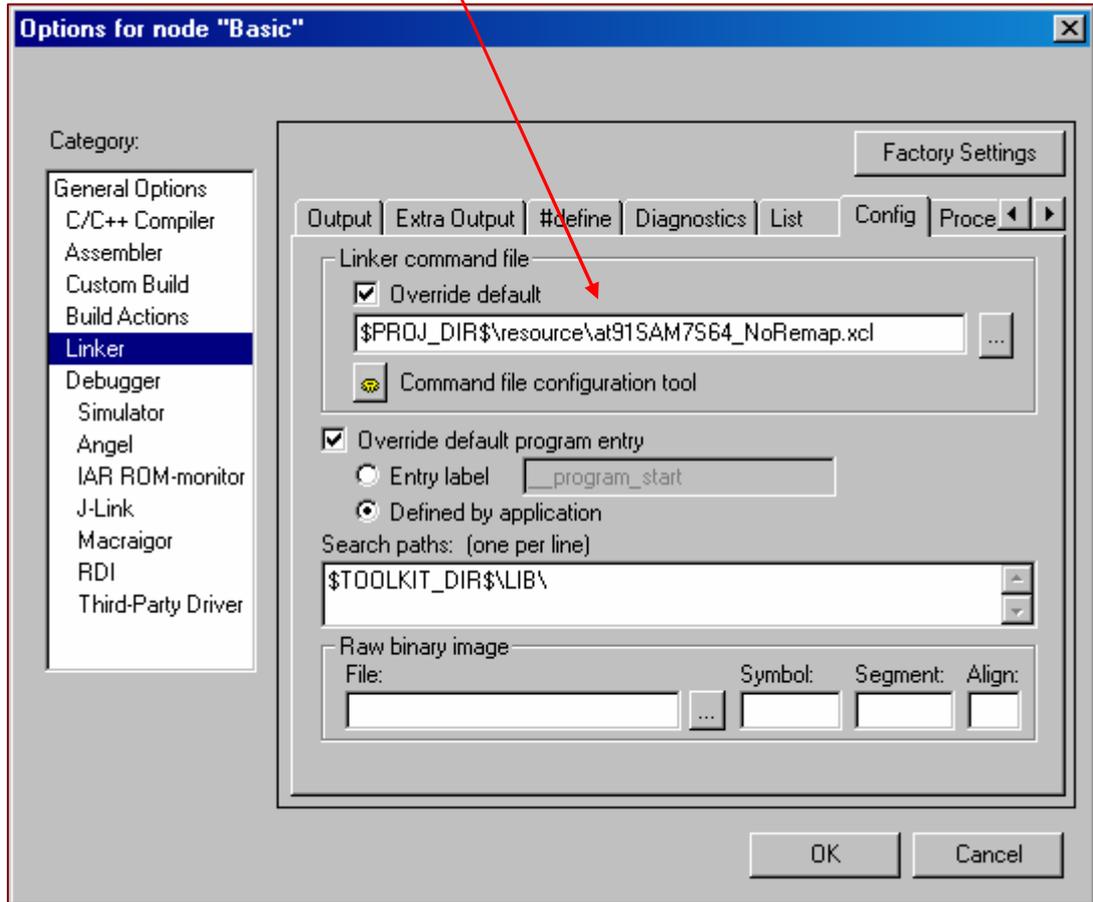


GETTING STARTED WITH ARM SAM7S64

Part 1

Keywords: Get started, Microcontroller, ARM, SAM7S64, ARM-JTAG, IAR EWARM

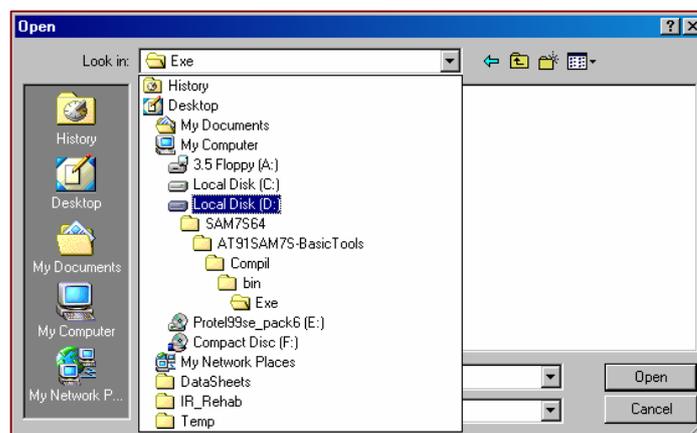
Another difference is the linker command file option. For *.bin output, we use **at91SAMS64_NoRemap.xcl**.



Compile and link again by **Build All** for this bin project.

Repeat the SAM-BA SYSTEM RECOVERY PROCEDURE under section 4.2 of this manual. Browse to Basic.bin in

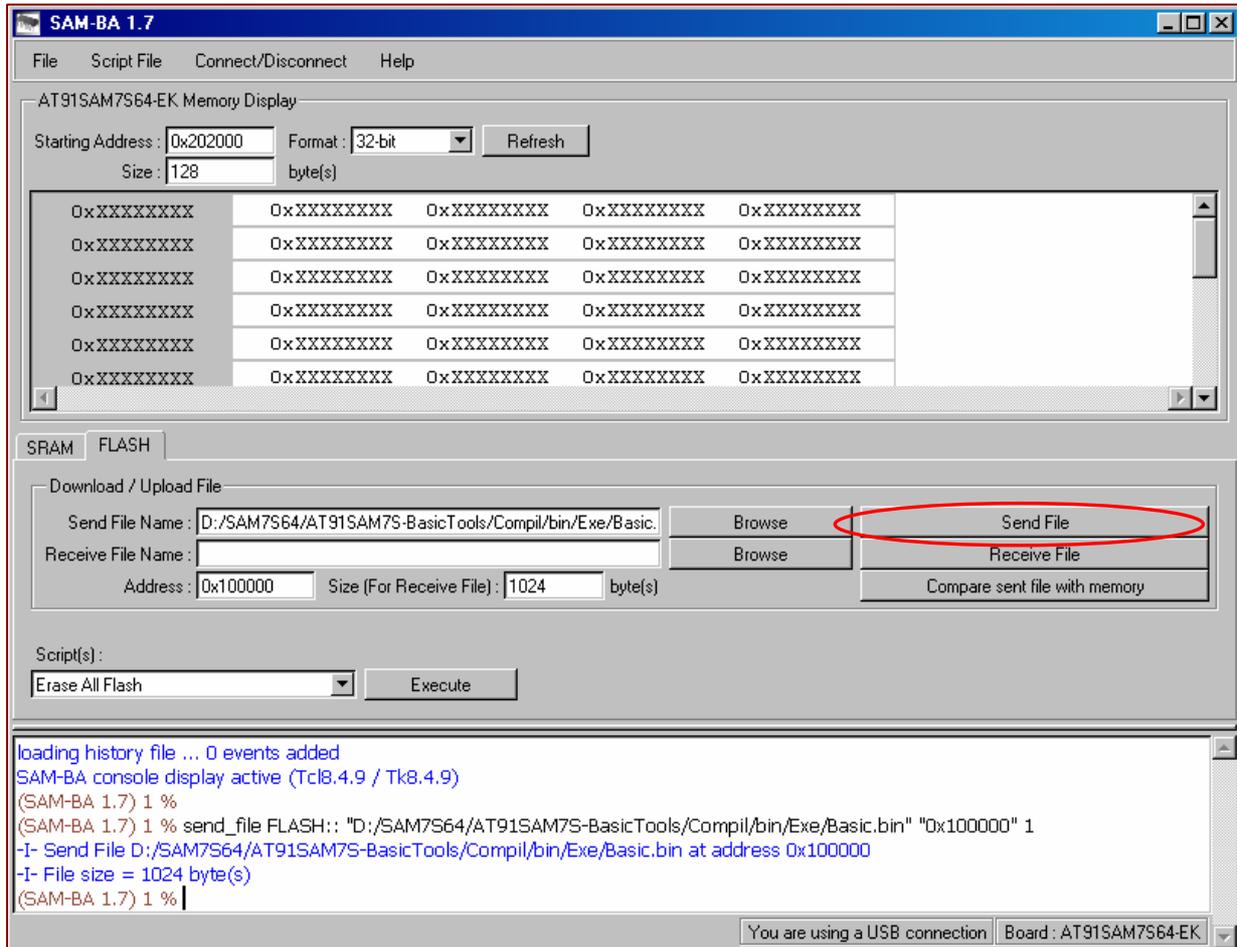
D:\SAM7S64\AT91SAM7S-BasicTools\Compil\bin\Basic.bin



GETTING STARTED WITH ARM SAM7S64

Part 1

Keywords: Get started, Microcontroller, ARM, SAM7S64, ARM-JTAG, IAR EWARM



Click **Send File** to program flash. Press RESET button onboard to see the result. Try pressing B1 and B2 to increase/decrease the blink rate.

GETTING STARTED WITH ARM SAM7S64

Part 1

Keywords: Get started, Microcontroller, ARM, SAM7S64, ARM-JTAG, IAR EWARM

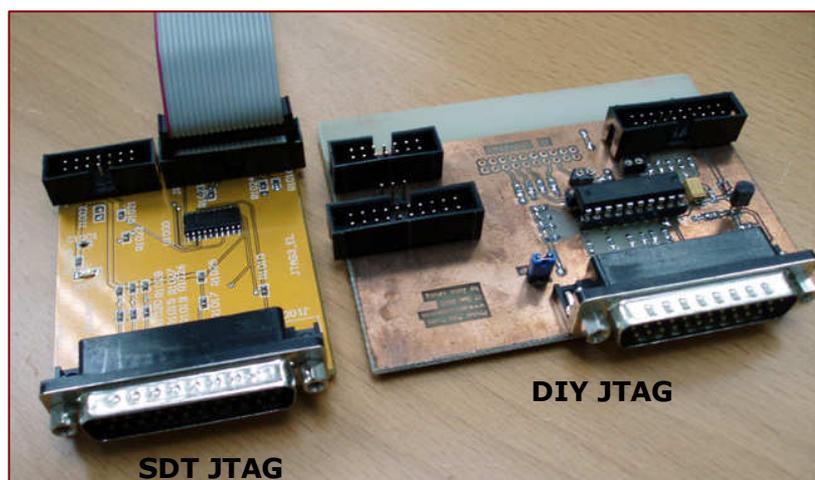
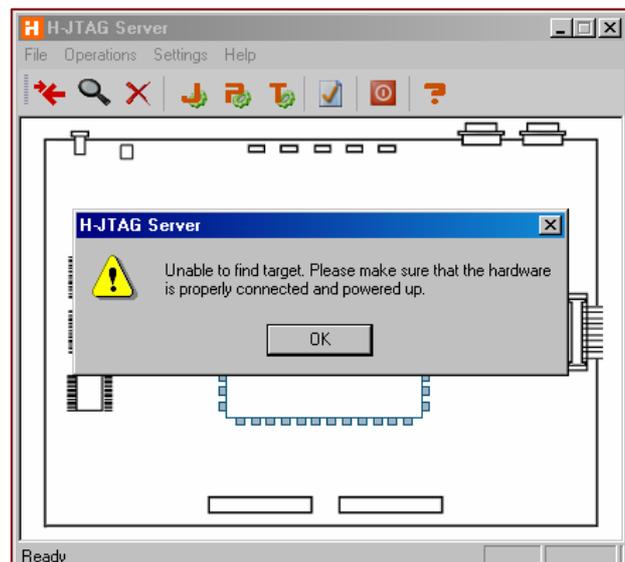
Appendix A : When ARM JTAG failed with my Windows 2000 workstation

To be honest, I didn't debug my first application that smooth as stated in this document. There are several PCs in the office. Some of them are Windows XP Chinese, while my main workstation for programming is a PIII 500 running Windows 2000 SP4.

When I used a Windows 2000 workstation, I just couldn't connect the ARM-JTAG with the SAM board. The following H-JTAG Server message came out no matter how I changed the **Settings**.

Finally, I just dig out an old **SDT JTAG** and a DIY JTAG that I have made some months ago. By using the same H-JTAG software driver, both of them worked; though I needed to change **Settings** to *sdt Jtag* for the yellow one as shown below.

For the **DIY JTAG**, I just use the same settings as Olimex JTAG.



Remarks: I still don't know why Olimex ARM-JTAG not willing to work on my Windows 2000 workstation. Anyway, it is OK with Windows XP

GETTING STARTED WITH ARM SAM7S64

Part 1

Keywords: Get started, Microcontroller, ARM, SAM7S64, ARM-JTAG, IAR EWARM

Appendix B : Why my first project didn't RESET?

There was an interesting finding in my first project. Right after I have programmed the chip with Basic.bin by SAM-BA, press on RESET button did reset the chip. This was within expectation from my experience with PIC / 8051. No matter what, a low on the RESET pin of a mcu will reset the chip, right?

However, after I have removed the power from the board and reconnect, the same RESET button no longer worked! Why?

A hint on page 70 of SAM7S64 data sheet : there is a Reset Controller handling all resets of the system.

I have to program the RSTC_MR register, setting the URSTEN bit to enable detection of a low level on the pin NRST for external reset! This URSTEN bit is 0 by default! In the main.c program, I have made the following line:

```
int main()
{
  /* Begin
   int i;
   ....
   /*AT91C_RSTC_RMR = (0xA500000|AT91C_RSTC_URSTEN);
   ....
  }
```

Uncomment this code and reprogram the chip, I have got a working NRST pin back! Up-to-now, I know there is much to learn with this little SAM!

...to be continued

14.4.3 Reset Controller Mode Register							
Register Name: RSTC_MR							
Access Type: Read/Write							
31	30	29	28	27	26	25	24
KEY							
23	22	21	20	19	18	17	16
-	-	-	-	-	-	-	BODIEN
15	14	13	12	11	10	9	8
ERSTL							
7	6	5	4	3	2	1	0
-	-	-	URSTIEN	-	-	-	URSTEN

- URSTEN: User Reset Enable**
0 = The detection of a low level on the pin NRST does not generate a User Reset.
1 = The detection of a low level on the pin NRST triggers a User Reset.
- URSTIEN: User Reset Interrupt Enable**
0 = USRSTS bit in RSTC_SR at 1 has no effect on rstc_irq.
1 = USRSTS bit in RSTC_SR at 1 asserts rstc_irq if URSTEN = 0.
- BODIEN: Brownout Detection Interrupt Enable**
0 = BODSTS bit in RSTC_SR at 1 has no effect on rstc_irq.
1 = BODSTS bit in RSTC_SR at 1 asserts rstc_irq.
- ERSTL: External Reset Length**
This field defines the external reset length. The external reset is asserted during a time of $2^{ERSTL+1}$ Slow Clock cycles. This allows assertion duration to be programmed between 60 μ s and 2 seconds.
- KEY: Password**
Should be written at value 0xA5. Writing any other value in this field aborts the write operation.